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Differential Equations Saber N. Elaydi, 1990-09-28 Reports and expands upon topics discussed at the International Conference on title held in Colorado Springs Colo June 1989 Presents recent advances in control oscillation and stability theories spanning a variety of subfields and covering evolution equations differential inclusions functi **Liapunov Functions and Stability in Control Theory** Andrea Bacciotti, Lionel Rosier, 2005-11-24 This book presents a modern and self contained treatment of the Liapunov method for stability analysis in the framework of mathematical nonlinear control theory A Particular focus is on the problem of the existence of Liapunov functions converse Liapunov theorems and their regularity whose interest is especially motivated by applications to automatic control Many recent results in this area have been collected and presented in a systematic way Some of them are given in extended unified versions and with new simpler proofs In the 2nd edition of this successful book several new sections were added and old sections have been improved e g about the Zubovs method Liapunov functions for discontinuous systems and cascaded systems Many new examples explanations and figures were added making this book accessible and well readable for engineers as well as mathematicians

Stability, Control and Differential Games Alexander Tarasyev, Vyacheslav Maksimov, Tatiana Filippova, 2020-05-29 This book presents the proceedings of the International Conference Stability Control Differential Games SCDG2019 September 16 20 2019 Yekaterinburg Russia organized by the Krasovskii Institute of Mathematics and Mechanics of the Ural Branch of the Russian Academy of Sciences Discussing the latest advances in the theory of optimal control stability theory and differential games it also demonstrates the application of new techniques and numerical algorithms to solve problems in robotics mechatronics power and energy systems economics and ecology Further the book includes fundamental results in control theory stability theory and differential games presented at the conference as well as a number of chapters focusing on novel approaches in solving important applied problems in control and optimization Lastly it evaluates recent major accomplishments and forecasts developments in various up and coming areas such as hybrid systems model predictive control Hamilton Jacobi equations and advanced estimation algorithms *Uncertain Dynamical Systems* A.A. Martynyuk, Yu. A. Martynyuk-Chernienko, 2011-11-28 This self contained book provides systematic instructive analysis of uncertain systems of the following types ordinary differential equations impulsive equations equations on time scales singularly perturbed differential equations and set differential equations Each chapter contains new conditions of stability of unperturbed motion of the above mentioned type of equations along with some applications Without assuming specific knowledge of uncertain dynamical systems the book includes many fundamental facts about dynamical behaviour of its solutions Giving a concise review of current research developments *Uncertain Dynamical Systems Stability and Motion Control* Details all proofs of stability conditions for five classes of uncertain systems Clearly defines all used notions of stability and control theory Contains an extensive bibliography facilitating quick access to specific subject areas in each chapter Requiring only a

fundamental knowledge of general theory of differential equations and calculus this book serves as an excellent text for pure and applied mathematicians applied physicists industrial engineers operations researchers and upper level undergraduate and graduate students studying ordinary differential equations impulse equations dynamic equations on time scales and set differential equations Stability and Control of Functional Differential Equations Matthew Monnig Peet,2006 *Scientific and Technical Aerospace Reports* ,1967 **Partial Stability and Control** Vladimir Il'ich Vorotnikov,1998 Partial Stability and Control develops a new efficient method of analysis and of control synthesis for problems on partial stability and control in dynamic systems described by ordinary differential equations including delay stochastic and uncertain systems The method is based on efficient procedures of transformation on initial systems or their subsystems for controlled systems and allows the solutions to be simplified In addition the method also allows many linear and nonlinear problems to be solved that cannot be easily done with available methods Ample attention is given to nonlinear game theoretical problems of reorientation of an asymmetric solid This book will be a valuable reference for advanced graduates and professionals in applied mathematics mechanics and control and control engineering who use stability theory and control methods

Stability and Control of Linear Systems Andrea Bacciotti,2018-11-02 This advanced textbook introduces the main concepts and advances in systems and control theory and highlights the importance of geometric ideas in the context of possible extensions to the more recent developments in nonlinear systems theory Although inspired by engineering applications the content is presented within a strong theoretical framework and with a solid mathematical background and the reference models are always finite dimensional time invariant multivariable linear systems The book focuses on the time domain approach but also considers the frequency domain approach discussing the relationship between the two approaches especially for single input single output systems It includes topics not usually addressed in similar books such as a comparison between the frequency domain and the time domain approaches bounded input bounded output stability including a characterization in terms of canonical decomposition and static output feedback stabilization for which a simple and original criterion in terms of generalized inverse matrices is proposed The book is an ideal learning resource for graduate students of control theory and automatic control courses in engineering and mathematics as well as a reference or self study guide for engineers and applied mathematicians Stability of Systems ,1965 Absolute Stability of Nonlinear Control Systems Xiaoxin Liao,Pei Yu,2008-07-16 Following the recent developments in the field of absolute stability Prof Xiaoxin Liao in conjunction with Prof Pei Yu has created a second edition of his seminal work on the subject Liao begins with an introduction to the Lurie problem and Lurie control system before moving on to the simple algebraic sufficient conditions for the absolute stability of autonomous and non autonomous ODE systems as well as several special classes of Lurie type systems The focus of the book then shifts toward the new results and research that have appeared in the decade since the first edition was published This book is aimed to be used by undergraduates in the areas of applied mathematics nonlinear

control systems and chaos control and synchronisation but may also be useful as a reference for researchers and engineers. The book is self-contained though a basic knowledge of calculus, linear system and matrix theory and ordinary differential equations is a prerequisite.

Partial Stability and Control V.I. Vorotnikov, 2012-12-06. Unlike the conventional research for the general theory of stability, this monograph deals with problems on stability and stabilization of dynamic systems with respect not to all but just to a given part of the variables characterizing these systems. Such problems are often referred to as the problems of partial stability stabilization. They naturally arise in applications either from the requirement of proper performance of a system or in assessing system capability. In addition, a lot of actual or desired phenomena can be formulated in terms of these problems and be analyzed with these problems taken as the basis. The following multispect phenomena and problems can be indicated: Lotka-Volterra ecological principle of extinction, focusing and acceleration of particles in electromagnetic fields, drift of the gyroscope axis, stabilization of a spacecraft by specially arranged relative motion of rotors connected to it. Also very effective is the approach to the problem of stability stabilization with respect to all the variables based on preliminary analysis of partial stability stabilization. A.M. Lyapunov, the founder of the modern theory of stability, was the first to formulate the problem of partial stability. Later works by V.V. Rumyantsev drew the attention of many mathematicians and mechanicians around the world to this problem, which resulted in its being intensively worked out. The method of Lyapunov functions became the key investigative method, which turned out to be very effective in analyzing both theoretic and applied problems.

Stability, Control and Application of Time-Delay Systems Qingbin Gao, Hamid Reza Karimi, 2019-06-27. *Stability Control and Application of Time Delay Systems* gives a systematic description of these systems. It includes adequate designs of integrated modeling and control and frequency characterizations. Common themes revolve around creating certain synergies of modeling, analysis, control, computing and applications of time delay systems that achieve robust stability while retaining desired performance quality. The book provides innovative insights into the state of the art of time delay systems in both theory and practical aspects. It has been edited with an emphasis on presenting constructive theoretical and practical methodological approaches and techniques. Unifies existing and emerging concepts concerning time delay dynamical systems. Provides a series of the latest results in large delay analysis and multi-agent and thermal systems with delays. Gives in each chapter numerical and simulation results in order to reflect the engineering practice.

Theory of Integro-Differential Equations V. Lakshmikantham, 1995-03-15. This unique monograph investigates the theory and applications of Volterra integro-differential equations. Whilst covering the basic theory behind these equations, it also studies their qualitative properties and discusses a large number of applications. This comprehensive work presents a unified framework to investigate the fundamental existence of theory, treats stability theory in terms of Lyapunov functions and functionals, develops the theory of integro-differential equations with impulse effects and deals with linear evolution equations in abstract spaces. Various applications of integro-differential equations such as population dynamics, nuclear

reactors viscoelasticity wave propagation and engineering systems are discussed making this book indispensable for mathematicians and engineers alike *Technical Abstract Bulletin* Defense Documentation Center (U.S.),1963 Advances in Stability Theory at the End of the 20th Century A.A. Martynyuk,2002-10-03 This volume presents surveys and research papers on various aspects of modern stability theory including discussions on modern applications of the theory all contributed by experts in the field The volume consists of four sections that explore the following directions in the development of stability theory progress in stability theory by first approximation contemporary developments in Lyapunov's idea of the direct method the stability of solutions to periodic differential systems and selected applications Advances in Stability Theory at the End of the 20th Century will interest postgraduates and researchers in engineering fields as well as those in mathematics *Proceedings of the ... ASME Design Engineering Technical Conferences* ,2003 Differential Equations, Stability, and Chaos in Dynamic Economics William A. Brock,A. G. Malliaris,1989 This is the first economics work of its kind offering the economist the opportunity to acquire new and important analytical tools It introduces the reader to three advanced mathematical methods by presenting both their theoretical bases and their applications to a wide range of economic models The mathematical methods presented are ordinary differential equations stability techniques and chaotic dynamics Topics such as existence continuation of solutions uniqueness dependence on initial data and parameters linear systems stability of linear systems two dimensional phase analysis local and global stability the stability manifold stability of optimal control and empirical tests for chaotic dynamics are covered and their use in economic theory is illustrated in numerous applications These applications include microeconomic dynamics investment theory macroeconomic policies capital theory business cycles financial economics and many others All chapters conclude with two sections on miscellaneous applications and exercises and further remarks and references In total the reader will find a valuable guide to over 500 selected references that use differential equations stability analysis and chaotic dynamics Graduate students in economics with a special interest in economic theory economic researchers and applied mathematicians will all benefit from this volume

Absolute Stability of Nonlinear Control Systems Xiao-Xin Liao,2013-04-17 As is well known a control system always works under a variety of accidental or continued disturbances Therefore in designing and analysing the control system stability is the first thing to be considered Classic control theory was basically limited to a discussion of linear systems with constant coefficients The fundamental tools for such studies were the Routh Hurwitz algebraic criterion and the Nyquist geometric criterion However modern control theory mainly deals with nonlinear problems The stability analysis of nonlinear control systems based on Liapunov stability theory can be traced back to the Russian school of stability In 1944 the Russian mathematician Lurie a specialist in control theory discussed the stability of an autopilot The well known Lurie problem and the concept of absolute stability are presented which is of universal significance both in theory and practice Up until the end of the 1950 s the field of absolute stability was monopolized mainly by Russian scholars such as A I Lurie M A Aizeman A M

Letov and others At the beginning of the 1960 s some famous American mathematicians such as J P LaSalle S Lefschetz and R E Kalman engaged themselves in this field Meanwhile the Romanian scholar Popov presented a well known frequency criterion and consequently made a decisive breakthrough in the study of absolute stability *Ordinary Differential Equations* Hartmut Logemann, Eugene P. Ryan, 2014-07-08 The book comprises a rigorous and self contained treatment of initial value problems for ordinary differential equations It additionally develops the basics of control theory which is a unique feature in current textbook literature The following topics are particularly emphasised existence uniqueness and continuation of solutions continuous dependence on initial data flows qualitative behaviour of solutions limit sets stability theory invariance principles introductory control theory feedback and stabilization The last two items cover classical control theoretic material such as linear control theory and absolute stability of nonlinear feedback systems It also includes an introduction to the more recent concept of input to state stability Only a basic grounding in linear algebra and analysis is assumed *Ordinary Differential Equations* will be suitable for final year undergraduate students of mathematics and appropriate for beginning postgraduates in mathematics and in mathematically oriented engineering and science

Nonlinear Analysis, Differential Equations and Control F.H. Clarke, R.J. Stern, 2012-12-06 Recent years have witnessed important developments in those areas of the mathematical sciences where the basic model under study is a dynamical system such as a differential equation or control process Many of these recent advances were made possible by parallel developments in nonlinear and nonsmooth analysis The latter subjects in general terms encompass differential analysis and optimization theory in the absence of traditional linearity convexity or smoothness assumptions In the last three decades it has become increasingly recognized that nonlinear and nonsmooth behavior is naturally present and prevalent in dynamical models and is therefore significant theoretically This point of view has guided us in the organizational aspects of this ASI Our goals were twofold We intended to achieve cross fertilization between mathematicians who were working in a diverse range of problem areas but who all shared an interest in nonlinear and nonsmooth analysis More importantly it was our goal to expose a young international audience mainly graduate students and recent Ph D s to these important subjects In that regard there were heavy pedagogical demands placed upon the twelve speakers of the ASI in meeting the needs of such a gathering The talks while exposing current areas of research activity were required to be as introductory and comprehensive as possible It is our belief that these goals were achieved and that these proceedings bear this out Each of the twelve speakers presented a mini course of four or five hours duration

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